

# A Constructive Subdivision of TQ-space

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Let us introduce a discrete dynamical system:

$$\mathbf{s}_{k+1} = \mathbf{f}(\mathbf{s}_k, \mathbf{p}), \quad \phi_{\mathbf{p}} : S \times K \rightarrow S, \quad \phi_{\mathbf{p}}(\mathbf{s}, k) \equiv \mathbf{f}^k(\mathbf{s}, \mathbf{p}), \quad (1)$$

with the properties:  $\mathbf{s} \in S \subset \mathbb{R}^N$ ,  $\mathbf{p} \in P \subset \mathbb{R}^L$ ,  $\mathbf{f} \in C^0(S \times P)$ ,  $k \in K \subseteq \mathbb{Z}$ ,  $n \in \overline{1, N}$ ,  $l \in \overline{1, L}$ , where  $\mathbf{s}$  is the variable of map state,  $\mathbf{p}$  is the vector of map parameters,  $k$  is discrete time. Let us also relate to the system (1) the trajectory of its state evolution  $\mathbf{s}$ :  $\{\mathbf{f}^k(\mathbf{s}, \mathbf{p})\}_{k \in K}$ , where  $\mathbf{f}^k$  is the composition of functions:

$$\mathbf{f}^w(\mathbf{s}, \mathbf{p}) = \mathbf{f}(\mathbf{f}(\dots \mathbf{f}(\mathbf{s}, \mathbf{p}), \mathbf{p}), \mathbf{p}), \quad \mathbf{f}^0(\mathbf{s}, \mathbf{p}) = \mathbf{s}.$$

Let us define the main map that encodes the shape of  $n$ -th component of the sequence  $\{\mathbf{s}_k\}$  in the space  $S \times K$  in terms of the finite T-alphabet:

$$\{\mathbf{s}_{k-1}^{(n)}, \mathbf{s}_k^{(n)}, \mathbf{s}_{k+1}^{(n)}\} \Rightarrow T_k^{\alpha\varphi}|_n, \quad T_k^{\alpha\varphi} = [T_k^{\alpha\varphi}|_1, \dots, T_k^{\alpha\varphi}|_N]. \quad (2)$$

For the relations that determine the map (2) see [1]. In the T-alphabet, all symbols are unambiguously divided into three separate classes  $T_o^{\alpha\varphi} = T_0^{\alpha\varphi} \cup T_s^{\alpha\varphi} \cup T_c^{\alpha\varphi}$ :

$$T_0^{\alpha\varphi} = \{\mathbf{T0}\}, \quad (3a)$$

$$T_s^{\alpha\varphi} = \{\mathbf{T1}, \mathbf{T2}, \mathbf{T4N}, \mathbf{T4P}, \mathbf{T6}, \mathbf{T7}, \mathbf{T8N}, \mathbf{T8P}\}, \quad (3b)$$

$$T_c^{\alpha\varphi} = \{\mathbf{T3N}, \mathbf{T3P}, \mathbf{T5N}, \mathbf{T5P}, \mathbf{T6S}, \mathbf{T6L}, \mathbf{T7S}, \mathbf{T7L}\}. \quad (3c)$$

In addition to the symbols  $T_k^{\alpha\varphi}|_n$  let us introduce symbols  $Q_k^{\alpha\varphi}|_n$ :

$$Q_k^{\alpha\varphi}|_n \equiv T_k^{\alpha\varphi}|_n \rightarrow T_{k+1}^{\alpha\varphi}|_n, \quad Q_k^{\alpha\varphi} = [Q_k^{\alpha\varphi}|_1, \dots, Q_k^{\alpha\varphi}|_n, \dots, Q_k^{\alpha\varphi}|_N].$$

All admissible transitions comprise a set of the alphabet symbols  $Q_o^{\alpha\varphi} \ni Q_k^{\alpha\varphi}|_n$ .

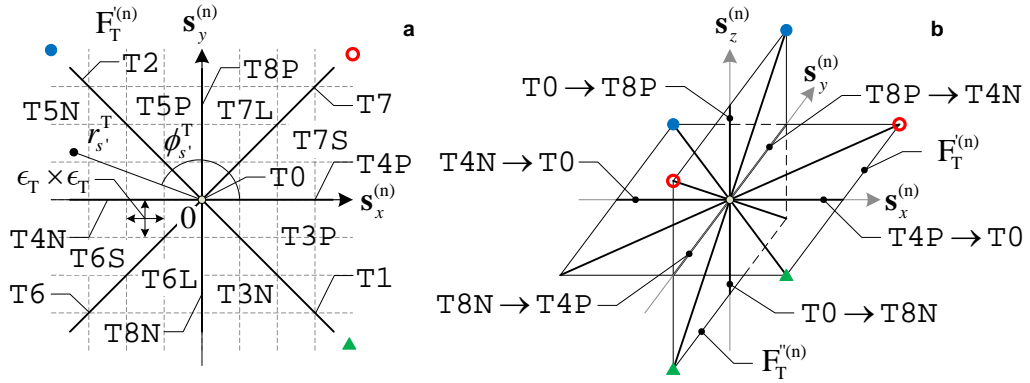
Let us introduce a representative point  $P_{Q_s}^{(n)} = (\mathbf{s}_x^{(n)}, \mathbf{s}_y^{(n)}, \mathbf{s}_z^{(n)}) \in P_{TQ}^{(n)} \subseteq \mathbb{R}^3$ :

$$\mathbf{s}_x = \mathbf{s} - \mathbf{f}(\mathbf{s}, \mathbf{p}), \quad \mathbf{s}_y = \mathbf{f}^2(\mathbf{s}, \mathbf{p}) - \mathbf{f}(\mathbf{s}, \mathbf{p}), \quad \mathbf{s}_z = \mathbf{f}^3(\mathbf{s}, \mathbf{p}) - \mathbf{f}^2(\mathbf{s}, \mathbf{p}), \quad (4)$$

which has the Cartesian coordinates that correspond to the state  $\mathbf{s}$  and unambiguously denote the state as a symbol of the  $Q_o^{\alpha\varphi}$  alphabet (by the  $n$ -th component of the state

space). Let us define a polar coordinate system  $(\mathbf{s}_x^{(n)}, \mathbf{s}_y^{(n)}) \Leftrightarrow (\phi_{s'}^T, r_{s'}^T)$ . Then (2) can be expressed as (see Fig. a):

$$\begin{array}{lll}
\text{T0} & r_{s'}^T = 0; & \text{T4N} & \phi_{s'}^T = 4\phi', & \text{T6L} & \phi_{s'}^T \in (5, 6)\phi', \\
r_{s'}^T > 0, & \phi' = \frac{\pi}{4} : & \text{T4P} & \phi_{s'}^T = 0\phi', & \text{T7S} & \phi_{s'}^T \in (0, 1)\phi', \\
\text{T1} & \phi_{s'}^T = 7\phi', & \text{T5N} & \phi_{s'}^T \in (3, 4)\phi', & \text{T7} & \phi_{s'}^T = 1\phi', \\
\text{T2} & \phi_{s'}^T = 3\phi', & \text{T5P} & \phi_{s'}^T \in (2, 3)\phi', & \text{T7L} & \phi_{s'}^T \in (1, 2)\phi', \\
\text{T3N} & \phi_{s'}^T \in (6, 7)\phi', & \text{T6S} & \phi_{s'}^T \in (4, 5)\phi', & \text{T8N} & \phi_{s'}^T = 6\phi', \\
\text{T3P} & \phi_{s'}^T \in (7, 8)\phi', & \text{T6} & \phi_{s'}^T = 5\phi', & \text{T8P} & \phi_{s'}^T = 2\phi'.
\end{array} \tag{5}$$



From formula (5) implies that subdivision of the subspace  $P_{TQ}^{(n)}$  into disjoint cubes:

$$S_x^{(n)}|m_x \times S_y^{(n)}|m_y \times S_z^{(n)}|m_z, \quad S_o^{(n)}|m_o = \epsilon_T \begin{cases} (m_o - 1, m_o] & m_o > 0, \\ 0 & m_o = 0, \\ [m_o, m_o + 1) & m_o < 0. \end{cases}, \tag{6}$$

determines natural extension over the T- and Q-alphabets, with codes of each alphabet symbol extended with the indices  $m_o$ , that set the number (and effectively the location) of the cell. Note that this subdivision preserves the Hausdorff dimension of the symbols in the T- and Q-alphabets in the subspace  $P_{TQ}^{(n)}$ .

Let us introduce a definition.

**Definition 1.** The graph  $\Gamma^{TQ} = \langle V^\Gamma, E^\Gamma \rangle$ , implies that:

$$\begin{aligned}
V^\Gamma &\subseteq T_o^{\alpha\varphi}|N, & E^\Gamma &\subseteq Q_o^{\alpha\varphi}|N, \\
\forall T^{\alpha\varphi} \in V^\Gamma &\Rightarrow \exists \mathbf{s}_0 \in S : T_1^{\alpha\varphi} = T^{\alpha\varphi}, & \forall \mathbf{s}_0 \in S &\Rightarrow \exists T^{\alpha\varphi} \in V^\Gamma : T_1^{\alpha\varphi} = T^{\alpha\varphi}, \\
\forall Q^{\alpha\varphi} \in E^\Gamma &\Rightarrow \exists \mathbf{s}_0 \in S : Q_1^{\alpha\varphi} = Q^{\alpha\varphi}, & \forall \mathbf{s}_0 \in S &\Rightarrow \exists Q^{\alpha\varphi} \in E^\Gamma : Q_1^{\alpha\varphi} = Q^{\alpha\varphi},
\end{aligned} \tag{7}$$

is a complete symbolic TQ-image of the dynamical system  $(S, K, \phi_p)$ .

Let us also define the full TQ-space:

$$P_{TQ} = P_{TQ}^{(1)} \times \cdots \times P_{TQ}^{(n)} \times \cdots \times P_{TQ}^{(N)}, \quad P_{TQ}^{(n)} = \text{Pr}_n P_{TQ}, \quad \dim P_{TQ} = 3N. \quad (8)$$

Then the consecutive subdivision of the space  $P_{TQ}$  through refinement of the cells  $S_x^{(n)}|m_x \times S_y^{(n)}|m_y \times S_z^{(n)}|m_z$  due to the parameter  $\epsilon_T \rightarrow 0$  results in a sequence of the graphs  $\{\Gamma_{\epsilon_T}^{TQ}\}_{\epsilon_T \in \mathcal{E}}$ .

When certain requirements are observed with regard to the nature of  $\epsilon_T$  change and the encoding scheme for  $m_o$  indices, the subdivision of the space  $P_{TQ}$  can be constructively applied to studying various properties of dynamical systems.

One of the simplest subdivision schemes is the dichotomous scheme. Let us define:

$$\epsilon_{T0}^{(n)} = \max \left| \left( \{s_x^{(n)}, s_y^{(n)}, s_z^{(n)}\} : s \in S_a \right) \right|, \quad \epsilon_{T_{r+1}}^{(n)} = \epsilon_{T_r}^{(n)}/2, \quad m_o = \overline{-d, 0, d}, \quad d = 2^r, \quad (9)$$

where  $S_a$  is the analyzed range of definition of the phase variable  $\mathbf{s}$ , for example, the attractor of the system  $(S, K, \phi_p)$ . When the dichotomous scheme is used, in terms of calculation the most efficient scheme of indexing the resulting  $P_{TQ}$ -space cells is octree, which allows to ignore the "empty" areas of the space.

In conclusion, it is worth mentioning that the proposed subdivision of the space  $P_{TQ}$  provides an opportunity to significantly increase the depth of performing certain tasks in terms of the symbolic CTQ-analysis: studying the T-synchronization of chaotic systems [2], estimating TQ-complexity of the trajectories of dynamical systems [1], analyzing the TQ-bifurcations [3] in discrete systems, etc. To this end, a set of theorems and propositions has been formulated and proved.

## References

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